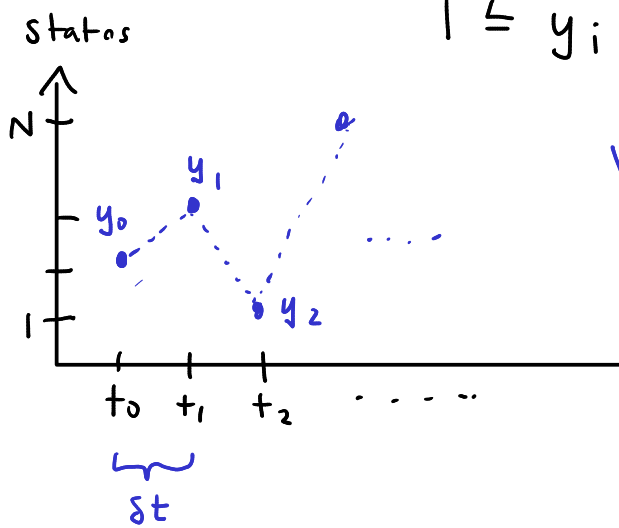


System variable  $y(t)$  = labels macrostate of system at time  $t$   
(could be vector)

discretize time  $t_i = i \delta t$   $i = 0, 1, 2, \dots$

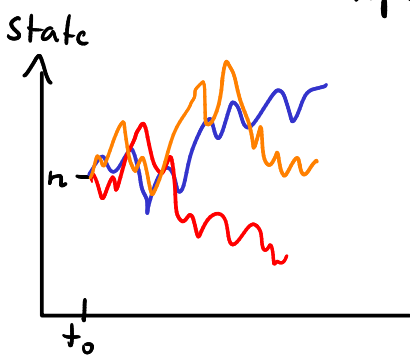
$y(t) \Rightarrow y(t_i) =$  integer labeling macrostate  
 $\equiv y_i$   
(discrete "addresses")

$1 \leq y_i \leq N = \#$  macrostates

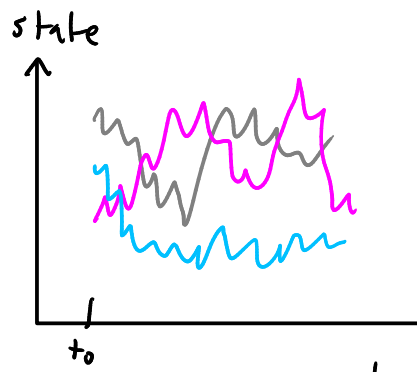


$V = (y_0, y_1, \dots, y_i)$   
= trajectory associated w/ single exper. run

ensemble = collection of traj. from many exper. runs



pure ensemble



mixed ensemble:

initial prob. dist. of states  $\mathcal{P}(y_0) = \delta_{y_0, n} = \begin{cases} 1 & y_0 = n \\ 0 & y_0 \neq n \end{cases}$   $\mathcal{P}(y_0)$  is not a delta

$\mathcal{P}(V) = \mathcal{P}(y_0, y_1, \dots, y_i) = \#$  traj. w/ seq.  $(y_0, y_1, \dots, y_i)$  in ensemble

prob. of observing  $V$  in ensemble

total # of traj's  
 $= N_{\text{traj}}$  (assume large)

$$\sum_{\nu} \mathcal{P}(\nu) = \sum_{y_0=1}^N \sum_{y_1=1}^N \cdots \sum_{y_i=1}^N \mathcal{P}(y_0, y_1, \dots, y_i) = 1$$

sum over all possible traj's

physical quantity  $Q(\nu)$  assoc. w/ traj.  $\nu$

ensemble avg.  $\langle Q \rangle \equiv \sum_{\nu} Q(\nu) \mathcal{P}(\nu)$

example:  $Q(\nu) = E_{y_i} - E_{y_0}$  (total energy change)

$$\langle Q(\nu) \rangle = \text{avg. total energy change}$$

Review of basic probability concepts:

- underlying ensemble
- let  $A$  &  $B$  be "events" drawn from ensemble

example:  $A = y_3$  state at time  $t_3$

or  $A = (y_0, y_1, y_2)$

$$\mathcal{P}(A) = \frac{\# \text{ traj where } A \text{ occurs}}{N_{\text{traj}}}$$

joint prob  $\mathcal{P}(A, B) = \frac{\# \text{ traj. where } A \text{ \& } B \text{ occur together}}{N_{\text{traj}}}$

$N_{\text{traj}}$

marginal prob.  $P(A) = \sum_B P(A, B)$

$$P(B) = \sum_A P(A, B)$$

all prob's sum to 1:  $\sum_A P(A) = 1$   $\sum_{A, B} P(A, B) = 1$   
 $\sum_B P(B) = 1$

conditional prob's: prob. of A given that B occurs

$$P(A | B) = \frac{\# \text{ traj. where } A \text{ \& } B \text{ occur together}}{\# \text{ traj. where } B \text{ occurs}}$$

$$= \frac{P(A, B)}{P(B)}$$

note:  $\sum_A P(A | B) = \sum_A \frac{P(A, B)}{P(B)} = \frac{1}{P(B)} P(B) = 1$

$$\sum_B P(A | B) = \sum_B \frac{P(A, B)}{P(B)} \neq 1 \text{ in general}$$

A, B can be in past / future relative to each other

if A & B are independent:  $P(A, B) = P(A)P(B)$

$$P(A | B) = \frac{P(A, B)}{P(B)} = P(A)$$

$$P(B | A) = P(B)$$

another property: Bayes theorem

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Proof:  $P(B|A) = \frac{P(A, B)}{P(A)}$

plug in RHS of Bayes:  $\frac{P(A, B)}{P(B)} = \underset{\text{LHS}}{P(A|B)}$

example:

1) statement: "I have 3 kids  
& at least one is a boy."

What is the prob. that I have 3 boys?

$\tilde{B}$  = at least 1 is a boy

BBB = all three are boys

$$P(BBB | \tilde{B}) = ?$$

all possible trajectories:

BBB  
BBG  
BGB  
GBB  
GGB  
GBG  
BGG  
GGG

$\tilde{B}$  is true  
in  
7 traj.

$$P(BBB | \tilde{B}) = \frac{1}{7}$$

check Bayes: 
$$\mathcal{P}(BBB | \tilde{B}) = \frac{\mathcal{P}(\tilde{B} | BBB) \mathcal{P}(BBB)}{\mathcal{P}(\tilde{B})}$$
$$= \frac{1 \cdot \frac{1}{8}}{\frac{7}{8}} = \frac{1}{7}$$