

last time:  $\vec{p}(t_{i+1}) = W(t_i) \vec{p}(t_i)$

$W_{nm}(t_i)$  = prob. to go to state  $n$   
if starting in state  $m$   
over time step  $\delta t$  at time  $t_i$

Properties of  $W$  matrix:

recall  $\sum_A P(A|B) = 1$

$\sum_{y_{i+1}} P(y_{i+1}|y_i) = 1$

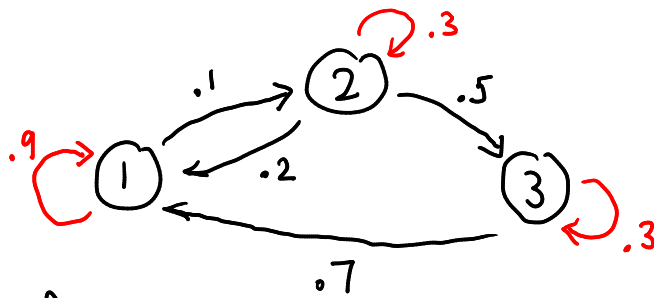
$\sum_n W_{nm}(t_i) = 1$

each column  
sums to 1

example:  
 $N=3$

		1	2	3	start
$W =$	1	0.9	0.2	0.7	every comp. is b/t 0 and 1
	2	0.1	0.3	0	
end	3	0	0.5	0.3	

graph:



=  $W$   
time-  
independ.

note: typically simplify  
by not drawing self arrows (red)  
but they are implicitly there

recall:  $P(v) = W_{n_i n_{i-1}}(t_{i-1}) \dots W_{n_1 n_0}(t_0) p_{n_0}(t_0)$

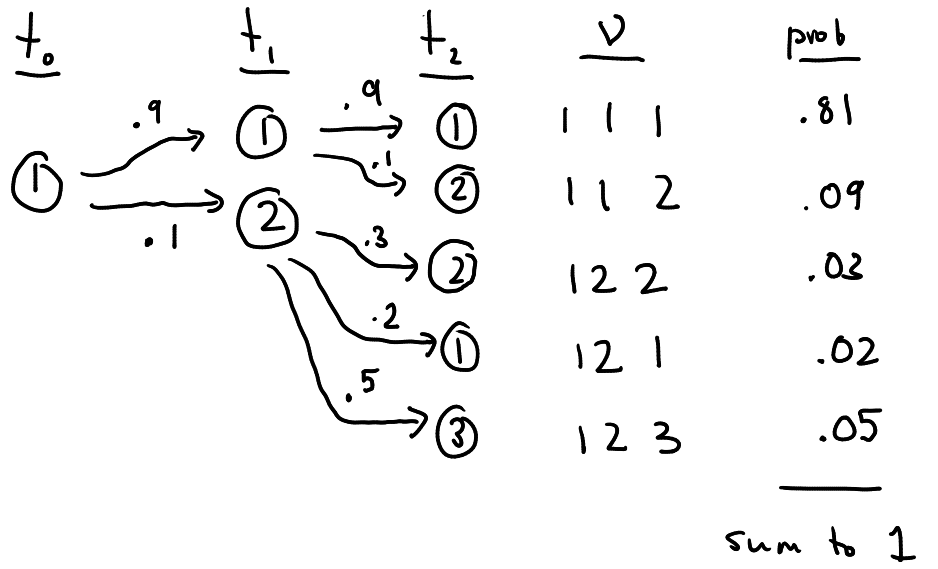
all possible three state trajectories:

in our example

$$\vec{p}(t_0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

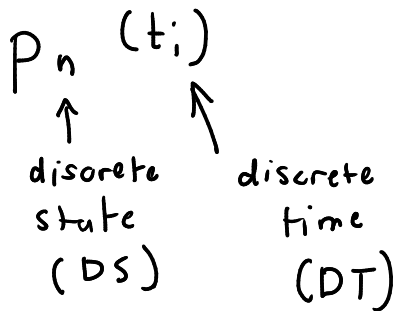
$$\vec{p}(t_1) = W \vec{p}(t_0) = \begin{pmatrix} .9 \\ .1 \\ 0 \end{pmatrix}$$

$$\vec{p}(t_2) = W \vec{p}(t_1) = \begin{pmatrix} .83 \\ .12 \\ .05 \end{pmatrix}$$



$$P(v) = W_{n_2, n_1} W_{n_1, n_0} \cdot p_{n_0}(t_0)$$

so far:



$$\vec{p}(t_{i+1}) = W(t_i) \vec{p}(t_i)$$

DS DT master equation

generalizations: continuous time (CT)  $t_i \rightarrow t$   
 and/or continuous state (CS)  
 $n \rightarrow x$  (i.e. position)

	DT	CT
DS	DTDS master equ. simulate trans. graph	CTDS master equ. kinetic Monte Carlo (Gillespie)
CS	numerical simulations	Fokker-Planck equ. Langevin equ.

keep track of states (blue)  
 keep track of trajectories (red)

Focus initially: DTDS b/c it's easiest to derive proofs

initially time-independent environmental conditions

$$W(t_i) = W$$

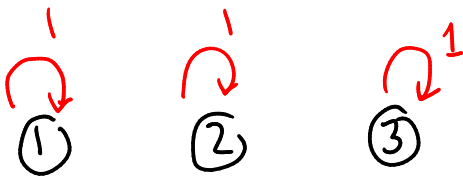
$$\vec{p}(t_n) = W^n \vec{p}(t_0)$$

observation:  $W^n$  seems to converge as  $n \rightarrow \infty$   
Why?

$W^n \xrightarrow{n \rightarrow \infty}$  const. matrix  
indep. of  $n$

$$\vec{p}(t_{n+2}) = W \underbrace{W^{n+1} \vec{p}(t_0)}_{\vec{p}(t_{n+1})} \quad \text{for large } n$$

$\vec{p}(t_{n+2}) \approx \vec{p}(t_{n+1}) \approx \vec{p}(t_n) \Rightarrow$  formally:  
 $\approx \vec{p}^s$  for large  $n$  there exists a vector  $\vec{p}^s$  such that  
 $\vec{p}^s = W \vec{p}^s$



$\vec{p}^s$  is called a stationary probability

- $\Rightarrow$
- 1) does it always exist?
  - 2) is it unique?
  - 3)  $W^n \vec{p}(t_0)$  is this guaranteed approach  $\vec{p}^s$  as  $n \rightarrow \infty$ ?