

$$\vec{p}(t_{i+1}) = W(t_i) \vec{p}(t_i)$$

$P_n(t_{i+1})$
 = prob. to observe state n at time t_{i+1}

$W_{nm}(t_i)$ = prob. to go to state n , given start at state m over time step Δt

recall: $\sum_A P(A|B) = 1$

$$\sum_{y_{i+1}} P(y_{i+1}|y_i) = 1$$

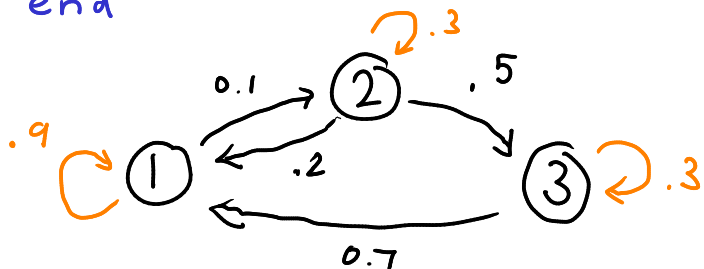
each column sums to 1

$$\sum_n W_{nm}(t_i) = 1$$

example:
 $N = 3$

$$W = \begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} & \text{start} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{pmatrix} 0.9 & 0.2 & 0.7 \\ 0.1 & 0.3 & 0 \\ 0 & 0.5 & 0.3 \end{pmatrix} \\ \text{end} & & \end{matrix}$$

graph:

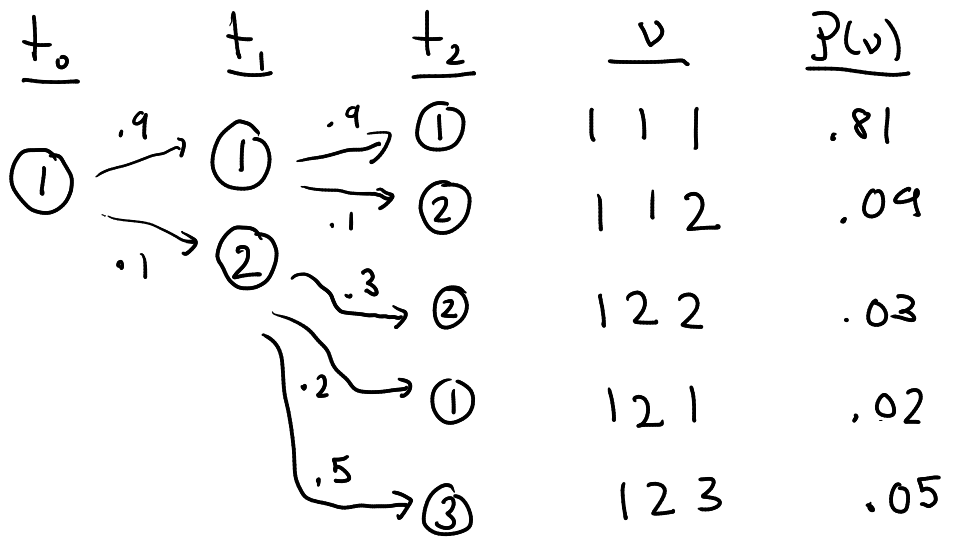


most of the time leave self arrows out (can work out values b/c columns sum to 1)

recall $P_{n_i, n_{i-1}}(t_{i-1}) \dots W_{n_i, n_0}(t_0) P_{n_0}(t_0)$
 $(n_0, n_1, \dots, n_{t_{i+1}})$

all possible 3 time step trajectories:

state prob's at each time step



$$\vec{p}(t_0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} \vec{p}(t_1) &= W \vec{p}(t_0) \\ &= \begin{pmatrix} .9 \\ .1 \\ 0 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{p}(t_2) &= W \vec{p}(t_1) \\ &= \begin{pmatrix} .83 \\ .12 \\ .05 \end{pmatrix} \end{aligned}$$

sum to 1

$$\sum_v P(v) = 1$$

so far:

$p_n(t_i)$
 ↑ ↖
 discrete state (DS) discrete time (DT)

$$\vec{p}(t_{i+1}) = W(t_i) \vec{p}(t_i)$$

DSDT

master equ.

generalizations: continuous time CT

$t_i \rightarrow t$

$\delta t \rightarrow 0$

continuous state CS

$n \rightarrow x$

	DT	CT
DS	DTDS master equ. simulate trans. graph	CTDS master equ. Kinetic Monte Carlo (gillespie)
CS	numerical simulations	Fokker-Planck equ. Langevin equ.

initial focus : DTDS



$\Delta x \rightarrow 0$: keep track of pos. x

$$\rightsquigarrow \frac{\partial p(x,t)}{\partial t} = D \frac{\partial^2 p(x,t)}{\partial x^2}$$

assume: time-independent envir. conditions

$$W(t_i) = W$$

$$\vec{p}(t_n) = W^n \vec{p}(t_0)$$

observation: W^n seems to converge as $n \rightarrow \infty$

Why?

$W^n \xrightarrow{n \rightarrow \infty}$ const. matrix indep. of n

$$\vec{p}(t_{n+2}) = W \underbrace{W^{n+1} \vec{p}(t_0)}_{\vec{p}(t_{n+1})} \quad \text{for large } n$$

$$\vec{p}(t_{n+2}) \approx \vec{p}(t_{n+1}) \approx \vec{p}(t_n)$$

$$\approx \vec{p}^s \quad \text{for large } n \quad \text{Stationary probability}$$

$$\Rightarrow \vec{p}^s = W \vec{p}^s \quad \begin{array}{l} \text{right e-vec} \\ \text{of } W \text{ w/} \\ \text{e-val } 1 \end{array}$$

\Rightarrow 1) does it always exist?

2) is it unique?

3) $W^n \vec{p}(t_0)$ is this guaranteed to approach \vec{p}^s as $n \rightarrow \infty$?

Question #1: does W always have at least one e-vec w/ e-val 1?

quick lemma: matrix M

$$\text{right e-vec: } M \vec{v} = \lambda \vec{v}$$

$$\Leftrightarrow \lambda \text{ is a sol'n of } \det(M - \lambda I) = 0$$

$$\text{left e-vec: } \vec{u}^T M = \delta \vec{u}^T$$

$$\text{transpose: } M^T \vec{u} = \delta \vec{u}$$

\Rightarrow δ is a sol'n of

$$\det(M^T - \delta I) = 0$$

$$\det((M - \delta I)^T) = 0$$

$$\det(M - \delta I) = 0$$

$$\det A^T = \det A$$

\Rightarrow left e-vals δ are same
as right e-vals

\Rightarrow if we know a left e-val
 δ exists \Rightarrow there must
exist a right e-vec \vec{v}
w/ $M\vec{v} = \delta\vec{v}$

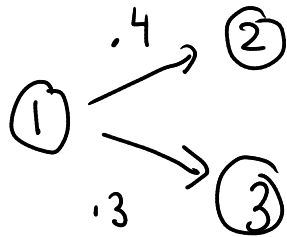
$M = W \Rightarrow$ claim there always exists
a left e-vec $\vec{u}^T = (1 \ 1 \ 1 \ \dots \ 1)$
w/ e-val $\underline{1}$

$$(1 \ 1 \ 1) \begin{pmatrix} .1 & .2 & .1 \\ .3 & .5 & .1 \\ .6 & .3 & .8 \end{pmatrix} = (1 \ 1 \ 1)$$

\Rightarrow works b/c
cols sum to $\underline{1}$

\Rightarrow there exists a right e-vec
 \vec{p}^s w/ e-val $\underline{1}$ (not necessarily
unique)

example:



$$W = \begin{array}{c} \begin{array}{cccc} & 1 & 2 & 3 & \text{start} \\ \begin{array}{l} 1 \\ 2 \\ 3 \end{array} & \begin{pmatrix} .3 & 0 & 0 \\ .4 & 1 & 0 \\ .3 & 0 & 1 \end{pmatrix} \end{array} \\ \text{end} \end{array}$$

$$P_A^S = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad P_B^S = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$P_C^S = \alpha \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + (1-\alpha) \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$0 \leq \alpha \leq 1$$

∞ of possible stationary states