

Example: result: ergodic net

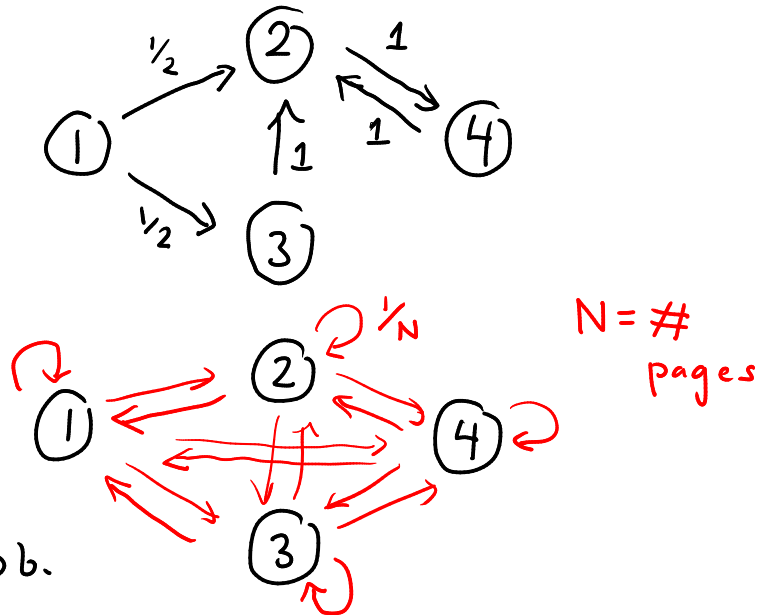
$$P_i^s = \frac{1}{h_{ii}}$$

Google Page Rank

→ = hyperlink

⓪ = webpage

W^H = "trans." matrix
created by
assigning equal prob.
to all outgoing arrows



W^c = trans. matrix
of red arrows

$$W_{ij}^c = \frac{1}{N} \text{ for all } i, j$$

$$W = \alpha W^H + \beta W^c$$

if $\alpha + \beta = 1 \Rightarrow$ columns of
 W sum to 1

\Rightarrow proper trans. matrix

$\beta > 0$: ergodic net

$$\alpha = .85$$

$$\beta = .15$$

\Rightarrow calculate $P_j^s = \frac{1}{h_{jj}}$ + use it to
rank webpages

not using N^2 equ's for h_{ij} to solve this

better approach:

starting w/ arbitrary \vec{p}_0

$$W \dots W W \vec{p}_0 \approx \vec{p}^s$$

\rightsquigarrow final puzzle piece: $W^n \vec{p}_0 \xrightarrow{?} \vec{p}^s$
as $n \rightarrow \infty$ for
any \vec{p}_0 ?

Next steps: develop a physical framework

classical mechanics
for "complex"
systems

\Rightarrow W
matrices

\swarrow \searrow
MR $W^n \vec{p}_0 = \vec{p}^s$
as $n \rightarrow \infty$

Mechanics in d-dimensions w/
M particles

$\vec{q} = dM$ coordinates for all particles } $2dM$
 $\vec{p} = dM$ momenta " " " } dim.
phase space

exact state of system $\Leftrightarrow (\vec{q}, \vec{p})$ in this
phase space

assumptions: system has finite vol. V
 no gain/loss of energy from outside

total energy (conserved) $E = \mathcal{H}(\vec{q}, \vec{p})$ Hamiltonian

1-dim. harm. oscillator ($m=1$)
 ($k=1$)

$$\mathcal{H} = \frac{1}{2} p_x^2 + \frac{1}{2} x^2 = E$$

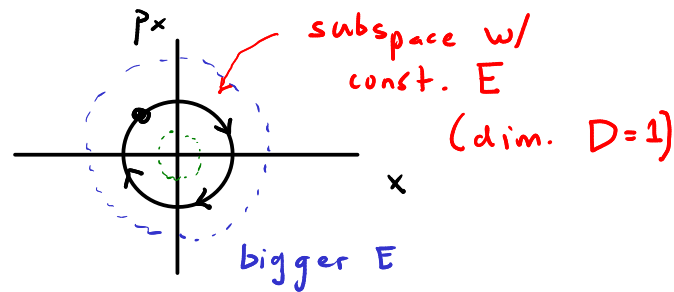
phase space: (x, p_x)

$$d=1, M=1$$

$2dM = 2$ -dim.
 phase space

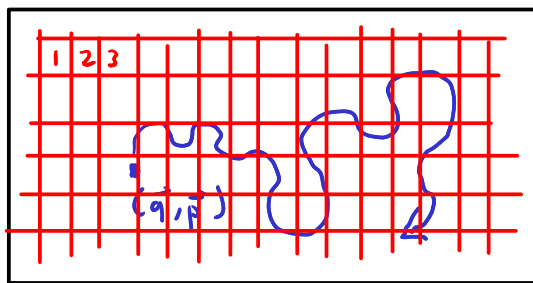
defines a subspace of const. E : is a phase space w/ dim.

$$2dM - 1 \equiv D$$



focus: a single subspace (one "layer" of the onion)
 = D -dim. surface

cartoon:

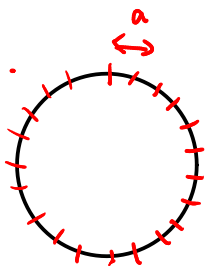


divide up surface into D -dim "boxes" of volume a

label boxes:

$$\mu = 1, 2, 3, \dots, \frac{\mathcal{H}(E)}{a}$$

↑
 leave out for simplicity



$$\text{radius} = \sqrt{2E}$$

$$\text{circumf} = 2\pi\sqrt{2E}$$

$$\mathcal{H}(E) = \frac{2\pi\sqrt{2E}}{a}$$