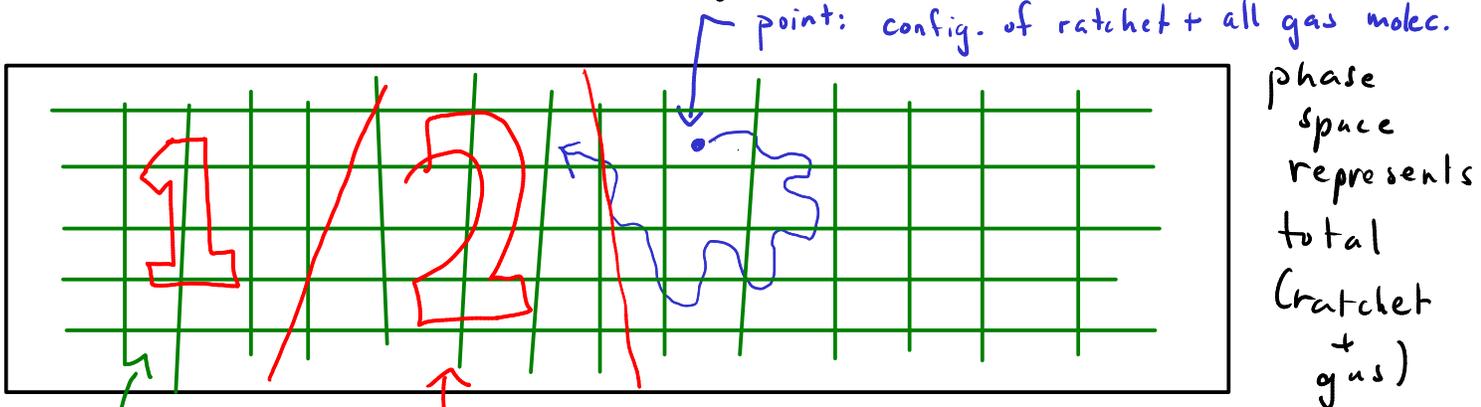


ratchet : states



energies : E_n

total (ratchet + gas) : $E_{tot} = E_n + E_n^{env}$



phase space represents total (ratchet + gas)

Const. E_{tot}

"macrostate": all pts where system is in state n

ergodicity + mixing : $P_\mu(t) \xrightarrow{t \rightarrow \infty} \frac{1}{\Omega(E_{tot})}$

$\Omega_n \equiv \#$ of microstates in macrostate n

($\#$ of cities in country n)

$\equiv \frac{1}{\underbrace{\Omega_{tot}}_{\text{total } \# \text{ of microstates on surface } (\# \text{ of cities})}}$

$$\Omega_{tot} = \sum_{i=1}^N \Omega_n \quad N = \# \text{ macrostates } (\# \text{ countries})$$

assumptions :

- environment has many more degrees of freedom than system

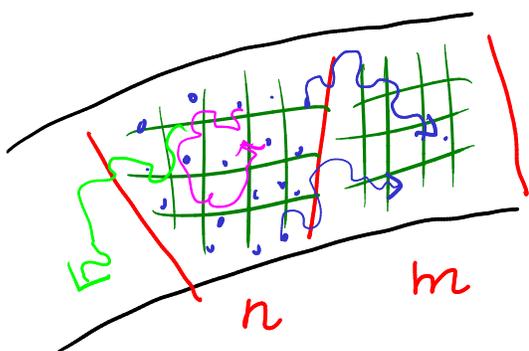
$$\textcircled{H}_h \gg N$$

$$\textcircled{H}_{\text{tot}} \gg N$$

- mixing is fast relative to timescales of interest
- dynamics of exploring w/ a macrostate happens faster than transitions b/t macrostates

\Rightarrow under this scenario: probability of visiting next macrostates depends at most on the current one ("memory" of deeper past is lost b/c of rapid randomization due to mixing)

Markov property



define trans. matrix

$$W_{mn} = \text{prob. to end up in } m \text{ after time interval } \delta t \text{ given start in } n$$

= $\frac{\# \text{ traj. that start in } n \text{ + end up in } m \text{ after } \delta t}{\# \text{ traj. " " " + end up anywhere after } \delta t}$

traj. " " " + end up anywhere after δt

$P_n(t_i) =$ prob. to be in macrostate n at time n

$\vec{p}(t_{i+1}) = W \vec{p}(t_i)$ DTDS master equ.

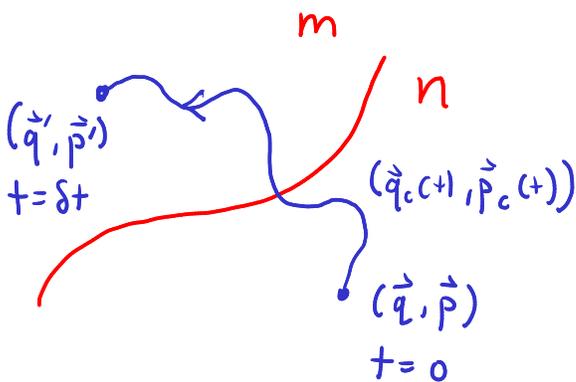
$P_M(t) \xrightarrow{t \rightarrow \infty} \frac{1}{\Omega_{tot}} \Rightarrow$
uniform distrib over all μ

$P_n(t) \xrightarrow{t \rightarrow \infty} \frac{\Omega_n}{\Omega_{tot}} \equiv P_n^S$
boxes in n
boxes total

stationary state

$W \vec{p}^S = \vec{p}^S$

Next step: use time reversal symmetry



classical traj. satisfies:

$\frac{d\vec{q}_c}{dt} = \frac{\partial H}{\partial \vec{p}_c} \quad \frac{d\vec{p}_c}{dt} = -\frac{\partial H}{\partial \vec{q}_c}$

Hamilton equations

"reversed solution" also satisfies these equations:

$$\vec{q}_r(\tilde{t}) \equiv \vec{q}_c(t - \tilde{t})$$

$$\vec{p}_r(\tilde{t}) \equiv -\vec{p}_c(t - \tilde{t})$$

