

irreversibility $I(v) = k_B \ln \frac{P(v)}{\tilde{P}(\tilde{v})}$

$$v = (n_0, n_1, \dots, n_\tau)$$

↑ rev. traj. in
rev. ensemble

define an avg. over all traj's in ensemble:

$$Q(v) = \text{traj. quantity}$$

$$Q \equiv \langle Q(v) \rangle = \sum_v P(v) Q(v)$$

$$\sum_{n_0} \dots \sum_{n_\tau}$$

calculate the following average:

$$\begin{aligned} \langle e^{-I(v)/k_B} \rangle &= \sum_v P(v) e^{-I(v)/k_B} \\ &= \sum_v P(v) \frac{\tilde{P}(\tilde{v})}{P(v)} \\ &= \sum_v \tilde{P}(\tilde{v}) \\ &= \sum_{\tilde{v}} \tilde{P}(\tilde{v}) = 1 \end{aligned}$$

IFT:

integral
fluctuation
theorem

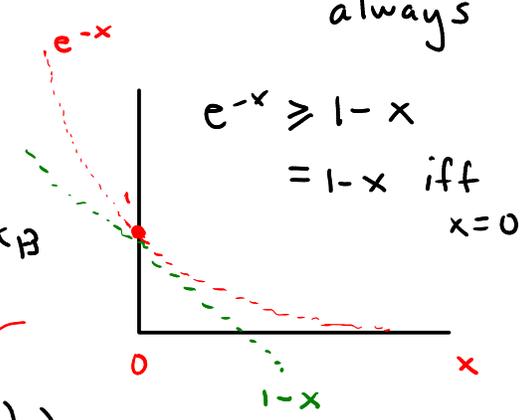
$$\langle e^{-I(v)/k_B} \rangle = 1$$

Seifert,
PRL 040602
(2005)
precursors:
1990's

Consequences:

1) Will prove: $\text{IFT} \Rightarrow \langle I(v) \rangle = I \geq 0$ always

proof:

$$\begin{aligned}
 1 &= \langle e^{-I(v)/k_B} \rangle \\
 &= \sum_v \mathcal{P}(v) e^{-I(v)/k_B} \\
 &\geq \sum_v \mathcal{P}(v) \left(1 - \frac{I(v)}{k_B} \right) \\
 &= \sum_v \mathcal{P}(v) - \frac{1}{k_B} \sum_v \mathcal{P}(v) I(v) \\
 &= 1 - \frac{1}{k_B} I \\
 \Rightarrow 1 &\geq 1 - \frac{I}{k_B} \Rightarrow \boxed{I \geq 0}
 \end{aligned}$$


2) you can decompose $I(v)$ into irreversibilities of single time step sub-trajectories:

$$\begin{aligned}
 v &= (n_0, n_1, \dots, n_\tau) \\
 &= \underbrace{(n_0, n_1)}_{\mu_0} \oplus \overbrace{(n_1, n_2)}^{\mu_1} \oplus \dots \oplus \underbrace{(n_{\tau-1}, n_\tau)}_{\mu_{\tau-1}}
 \end{aligned}$$

\uparrow
 "concatenation"

$$\mu_i = (n_i, n_{i+1}) \quad \text{RHS}$$

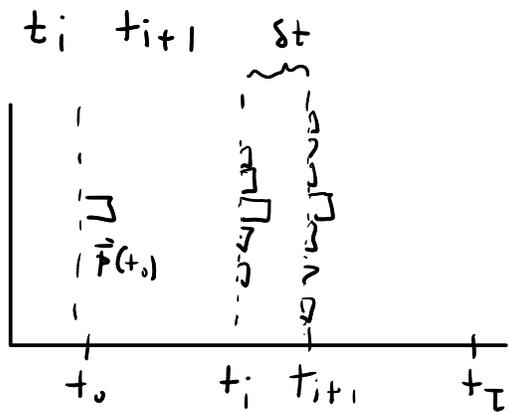
claim: $I(v) = I(\mu_0) + I(\mu_1) + \dots + I(\mu_{\tau-1})$

LHS

$$I(\mu_i) = k_B \ln \frac{\mathcal{P}(\mu_i)}{\tilde{\mathcal{P}}(\tilde{\mu}_i)} = k_B \ln \frac{W_{n_{i+1}n_i} P_{n_i}(t_i)}{W_{n_i n_{i+1}} \tilde{P}_{n_{i+1}}(t_i)}$$

" "

(n_i, n_{i+1}) P_{n_{i+1}}(t_{i+1})



$$\vec{p}(t_{i+1}) = W \vec{p}(t_i)$$

$$\text{RHS} = \sum_{i=1}^{\tau-1} I(\mu_i) = k_B \ln \left[\frac{W_{n_1 n_0} P_{n_0}(t_0)}{W_{n_0 n_1} P_{n_1}(t_1)} \cdot \frac{W_{n_2 n_1} P_{n_1}(t_1)}{W_{n_1 n_2} P_{n_2}(t_2)} \right. \\ \left. \dots \frac{W_{n_\tau n_{\tau-1}} P_{n_{\tau-1}}(t_{\tau-1})}{W_{n_{\tau-1} n_\tau} P_{n_\tau}(t_\tau)} \right]$$

$$= k_B \ln \frac{W_{n_\tau n_{\tau-1}} \dots W_{n_1 n_0} P_{n_0}(t_0)}{W_{n_0 n_1} \dots W_{n_{\tau-1} n_\tau} P_{n_\tau}(t_\tau)}$$

$$= k_B \ln \frac{\mathcal{P}(v)}{\tilde{\mathcal{P}}(\tilde{v})} = I(v) \quad \checkmark$$

Let's use these results:

IFT $\Rightarrow I \geq 0$ question: can $I = 0$?

focus on stationary state : \vec{p}^s

$$P_n(t_i) \rightarrow P_n^s$$

$$I(\mu_i) = k_B \ln \frac{W_{n_{i+1}n_i} P_{n_i}^s}{W_{n_i n_{i+1}} P_{n_{i+1}}^s}$$

imagine $I = \langle I(v) \rangle = 0 = \sum_i \langle I(\mu_i) \rangle$

we know $\langle I(\mu_i) \rangle \geq 0$

$$\Rightarrow \langle I(\mu_i) \rangle = 0$$

$$\Rightarrow I(\mu_i) = 0 \text{ for every possible } \mu_i$$

$$\Leftrightarrow W_{n_{i+1}n_i} P_{n_i}^s = W_{n_i n_{i+1}} P_{n_{i+1}}^s$$

$$\text{LDB : } W_{ij} P_j^s = W_{ji} P_i^s$$

if LDB true + we are at stationary state:

$$I(\mu_i) = 0 \text{ for every } \mu_i$$

$$I(v) = \sum_i I(\mu_i) = 0 \text{ for every traj. } v \text{ in stationary ensemble}$$

$$\Rightarrow \langle I(v) \rangle = 0 \text{ as well}$$

When $\bar{I}(v) = 0$ for all v in ensemble:
 $\langle I(v) \rangle = 0$: equilibrium stationary state (ESS)

any stationary state where $\langle I(v) \rangle > 0$:
nonequilibrium stationary state

